

MC60 GNSS AGPS Application Note

GSM/GPRS/GNSS Module Series

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Quectel Wireless Solutions Co., Ltd.

Office 501, Building 13, No.99, Tianzhou Road, Shanghai, China, 200233 Tel: +86 21 5108 6236 Email: info@guectel.com

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About the Document

History

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1.0	2016-08-02	Hyman DING	Initial
1.1	2016-08-18	Hyman DING	Updated the operation flow chart of QuecFastFix Online (figure 8)



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1 Introduction

This document mainly introduces the AGPS functions (EPOTM and QuecFastFix Online) of MC60's internal GNSS engine. The following chapters will describe the operation mechanism and processes of the two functions when MC60 is in **all-in-one** solution.





2 General Overview

MC60 is a multi-purpose module which integrates a high performance GNSS engine and a quad-band GSM/GPRS engine. The GNSS part supports both GPS and GLONASS systems which help achieve fast and accurate positioning.

The module features the built-in EPO^{TM 1)} technology which greatly reduces TTFF in cold start. EPO data, coupled with the reference location and real time information provided by QuecFastFix Online ²⁾ technology, further reduces the cold start TTFF to only several seconds (approx. 4.5 seconds).

As compared with modules with single GPS function, MC60 provides advantages as listed below:

- The internal GNSS engine supports GPS+GLONASS dual positioning systems, which achieves fast and accurate positioning.
- The built-in EPOTM technology is able to download 6 days' EPO data from MTK EPO server and store it in local file system, which speeds up positioning in cold start.
- Automatic EPO data download and update: MC60 can automatically check the validity of EPO data. If it detects that the EPO data has expired, it will automatically download the latest data from MTK EPO server.
- QuecFastFix Online function further reduces TTFF in cold start, making it close to the TTFF in hot start.

The following is the connection method between GSM and GNSS parts in **all-in-one** solution:



Figure 1: GSM and GNSS Connection in All-in-one Solution

NOTES

- 1. ¹⁾ EPO[™] (Extended Prediction Orbit) technology is developed by MTK. It helps the GNSS part to achieve improved TTFF in cold start state.
- ²⁾ QuecFastFix Online is a technology further used for improving TTFF. Based on EPO data, it is able to additionally provide real time and reference location information. This shortens the TTFF to several seconds in cold start, which is comparable to the TTFF in hot start. The function has to be triggered via AT+QGEPOAID command, and please refer to the *document [3]* for details.





3 Operation Mechanism and Processes

3.1. EPO[™] Operation Mechanism

After MC60 is powered on, the GNSS part has to be powered on separately via AT+QGNSSC=1 command. After that, AT+QGEPOAID command has to be executed to trigger EPOTM function. The function can also be triggered automatically through enabling EPOTM before powering on GNSS. EPOTM provides a great solution to improve the TTFF of the GNSS part.



3.2. EPO[™] Operation Processes

 EPO^{TM} function supports two kinds (Type A and Type B) of operation processes. Customers can choose any type according to demands.



3.2.1. Operation Processes of EPO[™] Function (Type A)

Before using EPOTM function, please make sure time synchronization has been completed and the module has registered on network successfully.

3.2.1.1. Detailed Operation Processes (Type A)

- 1) After MC60 is powered on, send AT+QGNSSC=1 to power ON the GNSS part to start positioning.
- 2) Configure PDP context and APN for network. Currently, EPO[™] function only supports PDP context 2.
- 3) Confirm whether MC60 has registered on network successfully.
- 4) Confirm whether time synchronization has been completed. MC60 will update local RTC time through NITZ via network. Some network operators may not support the function, and in this case, the time should be synchronized through NTP manually.
- 5) Enable EPO[™] function via **AT+QGNSSEPO=1** command and then execute **AT+QGEPOAID** command to trigger the function. For AT command details, please refer to *document [3]*.
- 6) Get NMEA information.

3.2.1.2. Example

AT+QGNSSC=1 OK AT+QIFGCNT=2 OK	// Power ON GNSS
AT+QICSGP=1,"CMNET	***
OK	
AT+CREG?;+CGREG?	// Check network status
+CREG: 0,2	
+CGREG: 0,2	
ок	
AT+CREG?;+CGREG?	// Check network status
+CREG: 0,1	
+CGREG: 0,1	
ОК	
AT+QGNSSTS?	// Read time synchronization status
+QGNSSTS: 1	// Time synchronization completed
ОК	
AT+QGNSSEPO=1	// Enable EPO TM function



OK AT+QGEPOAID // Trigger EPOTM function OK AT+QGNSSRD? +QGNSSRD: \$GNRMC,125349.093,V,...,0.00,0.00,010716,..,N*50

\$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125349.093,,,,,0,0,,,M,,M,,*54 \$GPGSA,A,1,,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125349.093,V,N*66

OK

AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125350.093,V,,,,,0.00,0.00,010716,,,N*58 \$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125350.093,,,,,0,0,,,M,,M,,*5C \$GPGSA,A,1,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125350.093,V,N*6E

OK

AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125353.092,A,3150.8278,N,11711.9888,E,0.31,111.02,010716,,,A*7C \$GNVTG,111.02,T,,M,0.31,N,0.58,K,A*2F \$GNGGA,125353.092,3150.8278,N,11711.9888,E,1,5,1.63,145.5,M,0.0,M,,*7A \$GPGSA,A,3,06,09,07,02,12,,,,,,1.83,1.63,0.83*0E \$GLGSA,A,3,,,,,,,,,1.83,1.63,0.83*1B \$GPGSV,4,1,15,02,68,022,28,05,61,286,,06,37,091,32,13,31,181,*73 \$GPGSV,4,2,15,19,25,155,,29,24,318,,20,18,257,,12,17,243,25*7E \$GPGSV,4,3,15,25,13,278,,09,11,039,31,07,06,081,26,15,06,205,*7A \$GPGSV,4,4,15,30,05,107,,17,01,151,,193,,,*44 \$GLGSV,1,1,04,85,77,105,,86,41,334,,84,26,139,,72,12,227,*65 \$GNGLL,3150.8278,N,11711.9888,E,125353.092,A,A*4B

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3.2.1.3. Operation Flow Chart



Figure 3: EPO[™] Function Operation Flow Chart (Operation Process A)



3.2.2. Operation Processes of EPO[™] Function (Type B)

This is the best solution for applications with high requirement on low power consumption. Customers can power ON the GNSS part after network has been registered on successfully and the time has been synchronized. After successful position fix, the GNSS part can be powered OFF to save power.

3.2.2.1. Detailed Operation Processes (Type B)

- 1) Configure PDP context and APN for network after power ON MC60. Currently, EPO[™] function only supports PDP context 2.
- 2) Confirm whether MC60 has registered on network successfully.
- 3) Confirm whether time synchronization has been completed. MC60 will update local RTC time through NITZ via GSM/GPRS network. Some network operators may not support the function, and in this case, the time should be synchronized through NTP manually.
- 4) Enable EPO[™] function via **AT+QGNSSEPO=1** command.
- 5) Power ON the GNSS part via AT+QGNSSC=1.
- 6) Get NMEA information.
- 7) Power OFF the GNSS part via AT+QGNSSC=0.

3.2.2.2. Example

AT+QIFGCNT=2 OK	// Set PDP context
AT+QICSGP=1,"CMNET OK	"// Configure APN
AT+CREG?;+CGREG? +CREG: 0,2	// Check network status
+CGREG: 0,2	
ок	
AT+CREG?;+CGREG? +CREG: 0,1	// Check network status
+CGREG: 0,1	
ок	
AT+QGNSSTS?	// Read time synchronization status
+QGNSSTS: 1	// Time synchronization completed
ок	
AT+QGNSSEPO=1	// Enable EPO^{TM} function



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// Power ON GNSS

OK

AT+QGNSSRD?

AT+QGNSSC=1

+QGNSSRD: \$GNRMC,125349.093,V,,,,,0.00,0.00,010716,,,N*50 \$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125349.093,,,,,0,0,,,M,,M,,*54 \$GPGSA,A,1,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125349.093,V,N*66

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AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125350.093,V,,,,,0.00,0.00,010716,,,N*58 \$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125350.093,,,,,0,0,,,M,,M,,*5C \$GPGSA,A,1,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125350.093,V,N*6E

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AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125353.092,A,3150.8278,N,11711.9888,E,0.31,111.02,010716,,,A*7C \$GNVTG,111.02,T,,M,0.31,N,0.58,K,A*2F \$GNGGA,125353.092,3150.8278,N,11711.9888,E,1,5,1.63,145.5,M,0.0,M,,*7A \$GPGSA,A,3,06,09,07,02,12,,,,,,,1.83,1.63,0.83*0E \$GLGSA,A,3,,,,,,,1.83,1.63,0.83*1B \$GPGSV,4,1,15,02,68,022,28,05,61,286,06,37,091,32,13,31,181,*73 \$GPGSV,4,2,15,19,25,155,,29,24,318,,20,18,257,,12,17,243,25*7E \$GPGSV,4,3,15,25,13,278,09,11,039,31,07,06,081,26,15,06,205,*7A \$GPGSV,4,4,15,30,05,107,,17,01,151,,193,,,*44 \$GLGSV,1,1,04,85,77,105,,86,41,334,,84,26,139,,72,12,227,*65 \$GNGLL,3150.8278,N,11711.9888,E,125353.092,A,A*4B

OK AT+QGNSSC=0 OK



3.2.2.3. Operation Flow Chart



Figure 4: EPO[™] Function Operation Flow Chart (Operation Process B)

3.2.3. The Influence of Time on EPO[™] Function

Time plays a very important role in EPO^{TM} function, and this is because:

- Before downloading EPO data, the system will check that whether the EPO data exits or has expired. During the process, if the time is incorrect, the local EPO data will be considered as expired.
- After power ON the GNSS part, the local time and EPO data will be pushed into the GNSS part successively. The local time will be used as an index to find out useful satellite information in EPO data. If the time is incorrect, EPO[™] function would not be triggered successfully.

NITZ NTP GNSS

There are three ways to realize time synchronization: NITZ, NTP and GNSS.

Figure 5: Three Ways for Time Synchronization

NOTES

- 1. NITZ for time synchronization: During network registration process after MC60 is powered on, it will get the real time through the network operator and then update the local RTC time. The function needs to be supported by the local network operator.
- 2. NTP for time synchronization: the module gets the real time through NTP domain.
- 3. GNSS for time synchronization: the module gets the real time from the satellite and then update the local RTC time.

After the module is powered on, the time will be synchronized automatically via NITZ while the module is registering to the local network operator. The synchronization status can be inquired through **AT+QGNSSTS**? command. In some areas, the local network operator may not support NITZ function, and in this case, **AT+QNTP=<server>[,<port>]** command can be executed to synchronize time through NTP domain. After the GNSS part is powered on, it can also get the real time from the satellite, and then update the RTC time if it has not been updated.

If the MCU of TE is able to provide exact RTC time, then the time can be synchronized to the module through **AT+CCLK** command.



NOTES

- 1. The time needed for time synchronization depends on the network quality. In general, the time is:
 - NITZ: about 10 seconds
 - NTP: about 50 seconds
- 2. The interval for time synchronization is about 12 hours.

3.2.4. EPO Data Download Processes

 EPO^{TM} is the abbreviation of Extended Prediction Orbit. EPO data is downloaded from MTK EPO server. After enabling EPO^{TM} function through **AT+QGNSSEPO=1** command, the module will download 6 days' EPO data from EPO server and store it in local file system. The process should be supported by GPRS network, so the network status needs to be confirmed before executing the command.



Figure 6: EPO Data Download Process



The system will start a 20s timer after executing **AT+QGNSSEPO=1**. When timeout, it will check whether the EPO data exists or has expired. If the EPO data is not existed or has expired, the system will start data downloading. If **AT+QGNSSC=1** is executed to power ON the GNSS part before the timer times out, and there is no latest EPO data available, the system will download 6 hours' EPO data first to speed up position fix. After timeout, it will start a new timer to continue downloading if the local EPO data is valid. A total of 6 days' EPO data will be downloaded into two files.

NOTE

Data size:

- 4KB for 6 hours' EPO data
- 96KB for 6 days' EPO data

3.3. QuecFastFix Online Function

QuecFastFix Online function can be used in combination with EPOTM technology to further improve TTFF and acquisition sensitivity in cold start. Based on the latest EPO data, QuecFastFix Online additionally offers adding information such as reference-location and NITZ/NTP time, which shortens TTFF to only several seconds (approx. 4.5s) in cold start. The function makes the cold start TTFF comparable to that in hot start.

After EPO data is pushed into GNSS, the reference location information will be pushed into GNSS automatically.



Figure 7: Operation Mechanism of QuecFastFix Online



NOTES

- 1. Real-time accuracy: ±3 seconds
- 2. Reference location accuracy: ±20km
- 3. The reference location can be acquired through QuecLocator, or the latest positioning information from GNSS.
- 4. Reference location range: -90°~90°(North Latitude), -180°~180°(East Longitude). Please refer to the document [3] for details.

3.3.1. Operation Processes

After power ON MC60, customers can set reference location information into the module, so as to further improve TTFF based on EPO^{TM} . The detailed processes (based on EPO^{TM} Operation Process Type B) are illustrated in *Chapter 3.3.2* and *Chapter 3.3.3*.

3.3.2. Example

AT+QIFGCNT=2 OK	// Set PDP context
AT+QICSGP=1,"CMNET' OK	// Configure APN
AT+CREG?;+CGREG? +CREG: 0,2	// Check network status
+CGREG: 0,2	
ОК	
AT+CREG?;+CGREG?	// Check network status
+CREG: 0,1	
+CGREG: 0,1	
ок	
AT+QGNSSTS?	// Read time synchronization status
+QGNSSTS: 1	// Time synchronization completed
ок	
AT+QGREFLOC=31.8443	376,117.204536 // Set reference location information for QuecFastFix Online
OK	714
AT+QGNSSEPO=1 OK	// Enable EPO [™] function
AT+QGNSSC=1 OK	// Power ON GNSS



AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125349.093,V,,,,,0.00,0.00,010716,,,N*50 \$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125349.093,,,,,0,0,,,M,,M,,*54 \$GPGSA,A,1,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125349.093,V,N*66

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AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125350.093,V,,,,,0.00,0.00,010716,,,N*58 \$GNVTG,0.00,T,,M,0.00,N,0.00,K,N*2C \$GNGGA,125350.093,,,,,0,0,,,M,,M,,*5C \$GPGSA,A,1,,,,,,*1E \$GLGSA,A,1,,,,,*02 \$GPGSV,1,1,02,09,,,29,06,,,29*74 \$GLGSV,1,1,00*65 \$GNGLL,,,,125350.093,V,N*6E

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AT+QGNSSRD?

+QGNSSRD: \$GNRMC,125353.092,A,3150.8278,N,11711.9888,E,0.31,111.02,010716,,,A*7C \$GNVTG,111.02,T,,M,0.31,N,0.58,K,A*2F \$GNGGA,125353.092,3150.8278,N,11711.9888,E,1,5,1.63,145.5,M,0.0,M,,*7A \$GPGSA,A,3,06,09,07,02,12,,,,,,1.83,1.63,0.83*0E \$GLGSA,A,3,,,,,,,1.83,1.63,0.83*1B \$GPGSV,4,1,15,02,68,022,28,05,61,286,,06,37,091,32,13,31,181,*73 \$GPGSV,4,2,15,19,25,155,,29,24,318,,20,18,257,,12,17,243,25*7E \$GPGSV,4,3,15,25,13,278,,09,11,039,31,07,06,081,26,15,06,205,*7A \$GPGSV,4,4,15,30,05,107,,17,01,151,,193,,,*44 \$GLGSV,1,1,04,85,77,105,,86,41,334,,84,26,139,,72,12,227,*65 \$GNGLL,3150.8278,N,11711.9888,E,125353.092,A,A*4B

OK AT+QGNSSC=0 OK



3.3.3. Operation Flow Chart



Figure 8: QuecFastFix Online Operation Flow Chart



NOTE

QuecFastFix Online shortens GNSS's cold start TTFF to 4.5s (reference only) in OpenSky.







4.1. Related Documents

Table 1: Related Documents

SN	Document Name	Remark
[1]	NMEA 0183 Version 3.01	Standard for Interfacing Marine Electronic Devices
[2]	Quectel_MC60_Hardware_Design	MC60 Hardware Design
[3]	Quectel_MC60_GNSS_AT_Commands_Manual	MC60 GNSS AT Commands Manual
[4]	Quectel_MC60_AT_Commands_Manual	MC60 AT Commands Manual

4.2. Terms and Abbreviations

Table 2: Terms and Abbreviations

Abbreviation	Description
AGPS	Assisted Global Positioning System
EPO	Extended Prediction Orbit
GGA	Global Positioning System Fixed Data
GLL	Geographic Position – Latitude/Longitude
GLONASS	Global Navigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
GSA	GNSS DOP and Active Satellites



GSM	Global System for Mobile Communication
GSV	GNSS Satellites in View
NITZ	Network Identity and Time Zone
NMEA	National Marine Electronics Association
NTP	Network Time Protocol
RMC	Recommended Minimum Specific GNSS Data
TE	Terminal Equipment
VTG	Course Over Ground and Ground Speed

